

HDR

# TECHNOLOGY OVERVIEW: AUTONOMOUS VEHICLES

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# CONNECTED CAR

## Internet Connectivity

- Cellular Connectivity/WiFi Hotspot
- Infotainment Systems
- Smartphone Extension
- Telematics and Remote Access



Source: Google

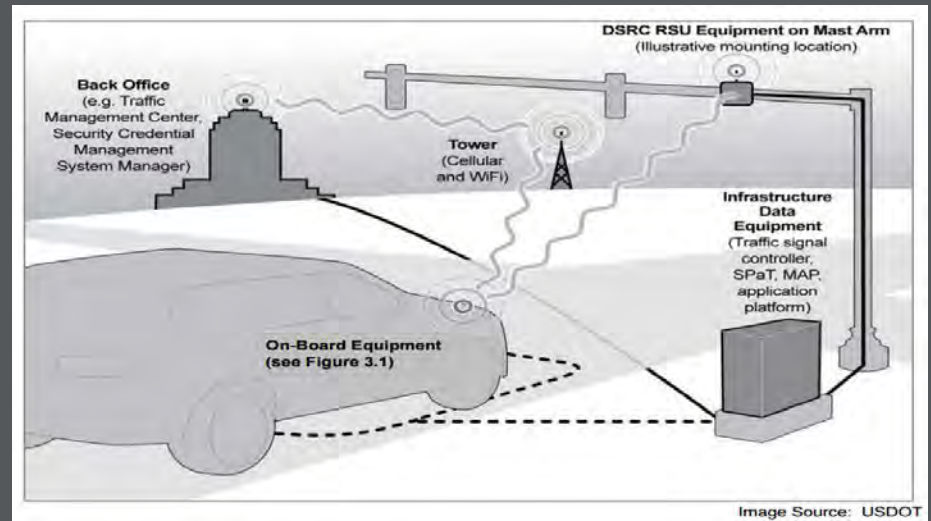


Source: Apple

# CONNECTED VEHICLE

## Point-to-Point Wireless Communications

- Dedicated Short Range Communications
- V2V (Vehicle-to-Vehicle)
- V2I (Vehicle-to-Infrastructure)
- V2X (Vehicle-to-All)
- Low Latency Wireless (Milliseconds)
  - 5.9 GHz
  - 802.11p wireless router, IEEE1609.X



# AUTONOMOUS VEHICLES

- How do they work?

## Under the bonnet

How a self-driving car works

Signals from **GPS (global positioning system)** satellites are combined with readings from tachometers, altimeters and gyroscopes to provide more accurate positioning than is possible with GPS alone

**Radar sensor**

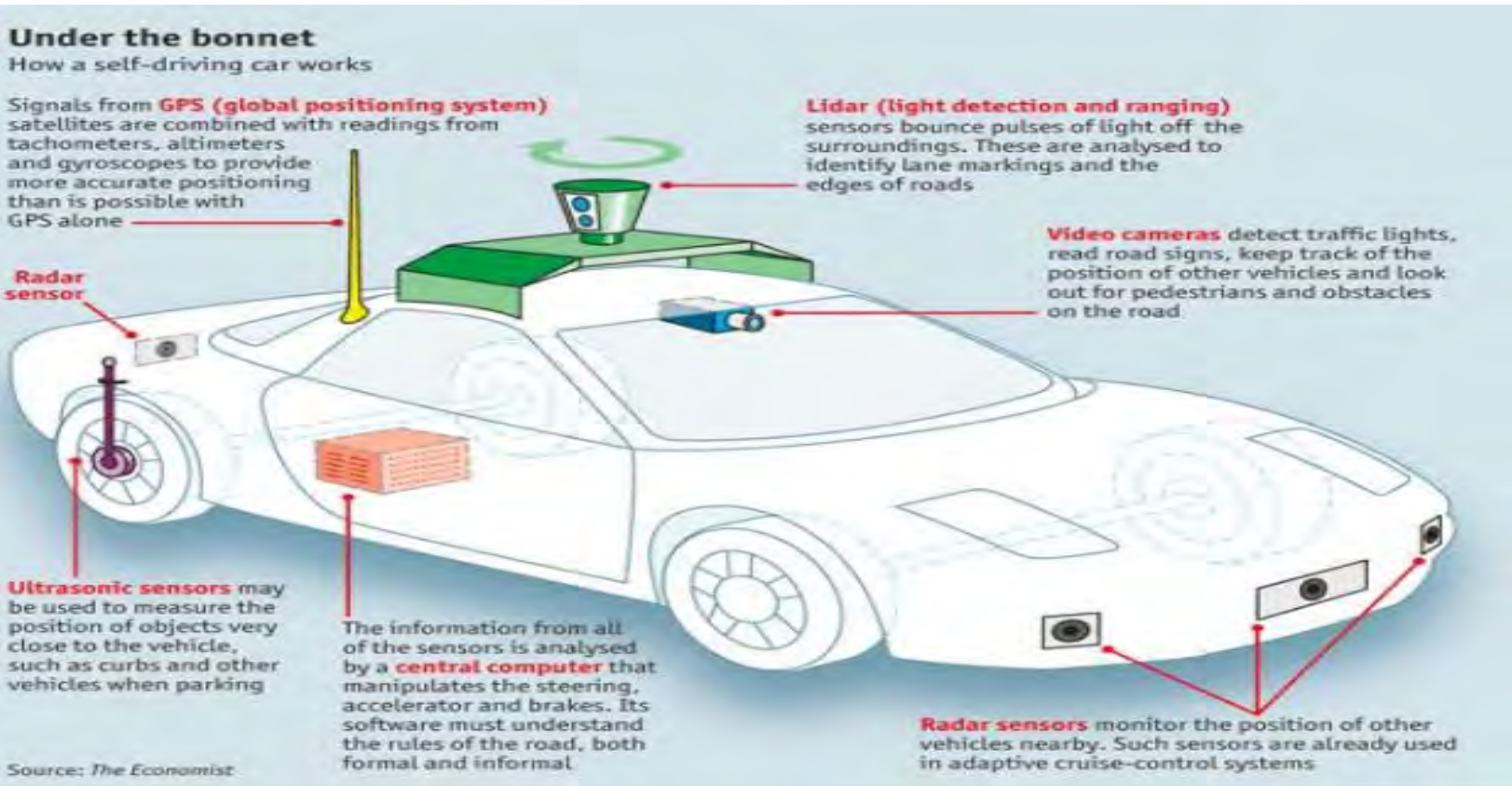
**Ultrasonic sensors** may be used to measure the position of objects very close to the vehicle, such as curbs and other vehicles when parking

The information from all of the sensors is analysed by a **central computer** that manipulates the steering, accelerator and brakes. Its software must understand the rules of the road, both formal and informal

**Lidar (light detection and ranging)** sensors bounce pulses of light off the surroundings. These are analysed to identify lane markings and the edges of roads

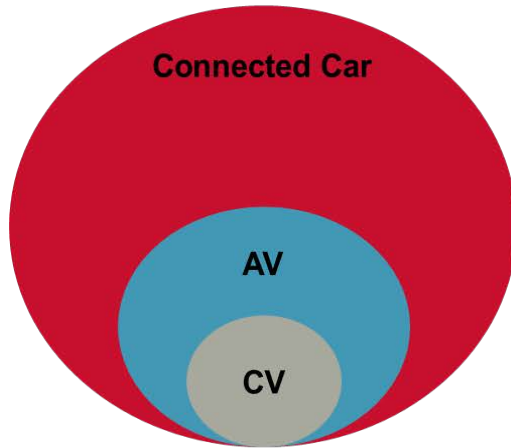
**Video cameras** detect traffic lights, read road signs, keep track of the position of other vehicles and look out for pedestrians and obstacles on the road

**Radar sensors** monitor the position of other vehicles nearby. Such sensors are already used in adaptive cruise-control systems

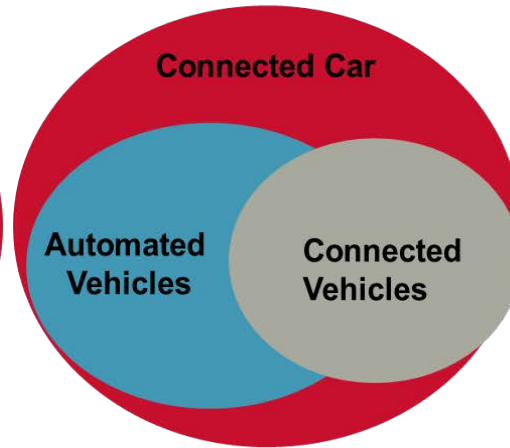


# RELATIONSHIP BETWEEN CONNECTED CARS, CONNECTED VEHICLES AND AUTONOMOUS VEHICLES

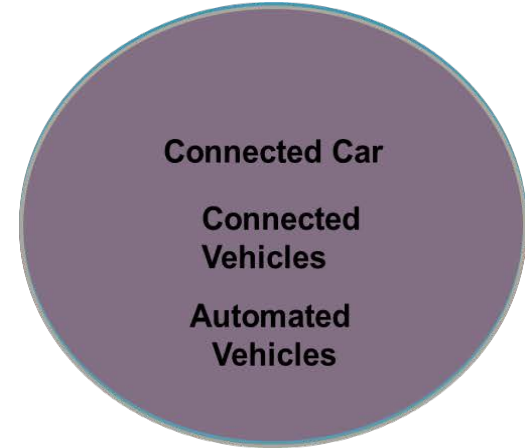
- Cars connected to Internet
- Some Level of Autonomy
- CVs in Pilot Deployments
- Cars connected to Internet
- AV production vehicles (Level 3)
- CVs in Production Vehicles
- Cars Connected to Internet
- AV production vehicles (Level 4)
- CVs Ubiquitous



Today



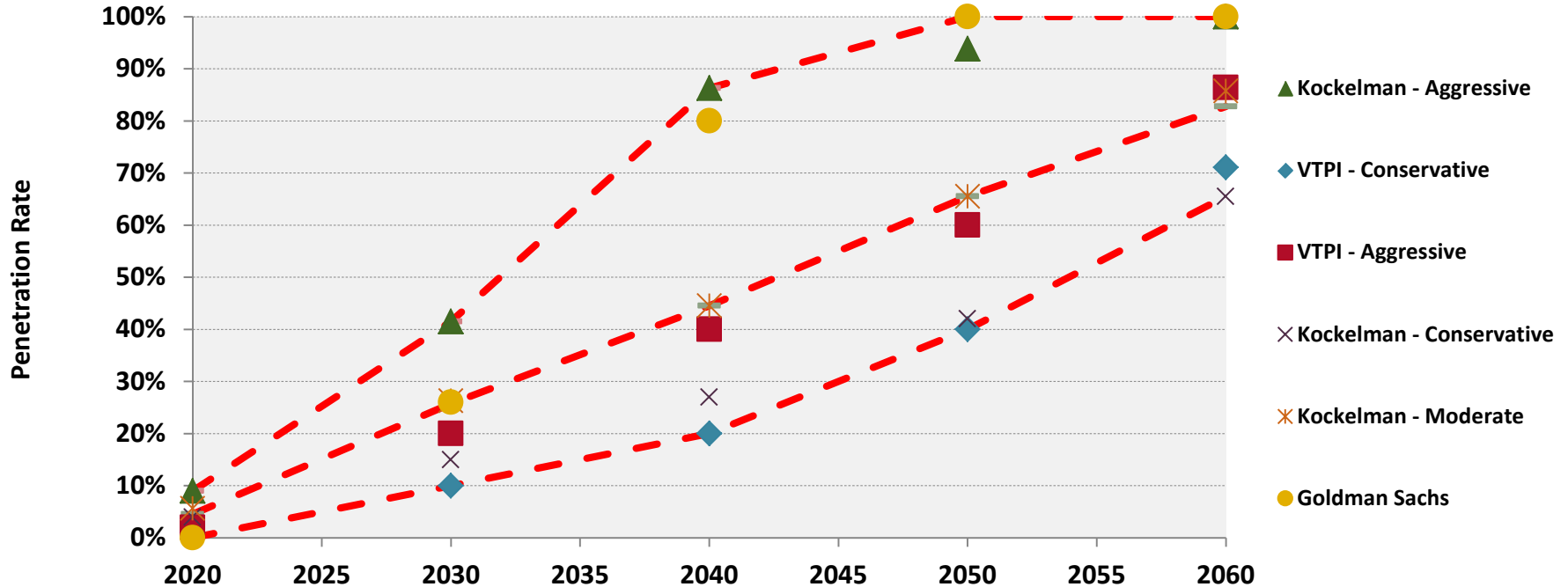
1-3 Years



7-15 Years






















# AUTONOMOUS VEHICLES – LITERATURE PROJECTIONS

Passenger Vehicle Fleet Adoption of Level 3 or above: 10% to 40% by 2030



# AUTONOMOUS VEHICLES

For on-road vehicles

		 Human driver	 Automated system		
		Steering and acceleration/ deceleration	Monitoring of driving environment	Fallback when automation falls	Automated system is in control
Human driver monitors the road	<b>0</b> NO AUTOMATION				N/A
	<b>1</b> DRIVER ASSISTANCE				SOME DRIVING MODES
	<b>2</b> PARTIAL AUTOMATION				SOME DRIVING MODES
Automated driving system monitors the road	<b>3</b> CONDITIONAL AUTOMATION				SOME DRIVING MODES
	<b>4</b> HIGH AUTOMATION				SOME DRIVING MODES
	<b>5</b> FULL AUTOMATION				





# AUTONOMOUS VEHICLE MANUFACTURERS (TRANSIT)



## Olli by Local Motors

- 12 passenger
- Electric
- Lidar and Optical
- Human Monitored
- Based upon IBM Watson
- Deployed (Pilots) 2016
  - Washington, DC
  - Miami
  - Los Vegas



## EZ10 by EasyMile

- 12 passenger
- Electric
- Deployed (Pilots) 2016
  - Helsinki, Finland
  - Concord, California
  - Singapore (2015)
  - Tampa Florida (2017)
- 1.5M rides



## ARMA by Navya

- 15 passenger
- Electric
- Lidar, Optical, GPS
- Deployed (Pilots)
  - Cologne
  - Germany
  - Australia
- Deployed
  - SION (2016)

# AUTONOMOUS TRANSIT

## Physical and Operational Characteristics (EasyMile EZ10)

- Three Modes of Operation
  - Traditional Metro (every stop)
  - Commuter (Stop on demand)
  - On-Demand (Dynamic Transit) for First Mile/Last Mile
- 12 Passenger
  - 6 seated, 6 standing
- Electrically Powered
  - **Battery:** Lithium-ion (LiFeP04)
  - **Battery Charger:** 230V 16A
  - 14 hours running on single charge



Length	12.9 ft	Cruising Speed	12.4 mph
Width	6.5 ft		
Height	9.0 ft	Max Speed	24.9 mph

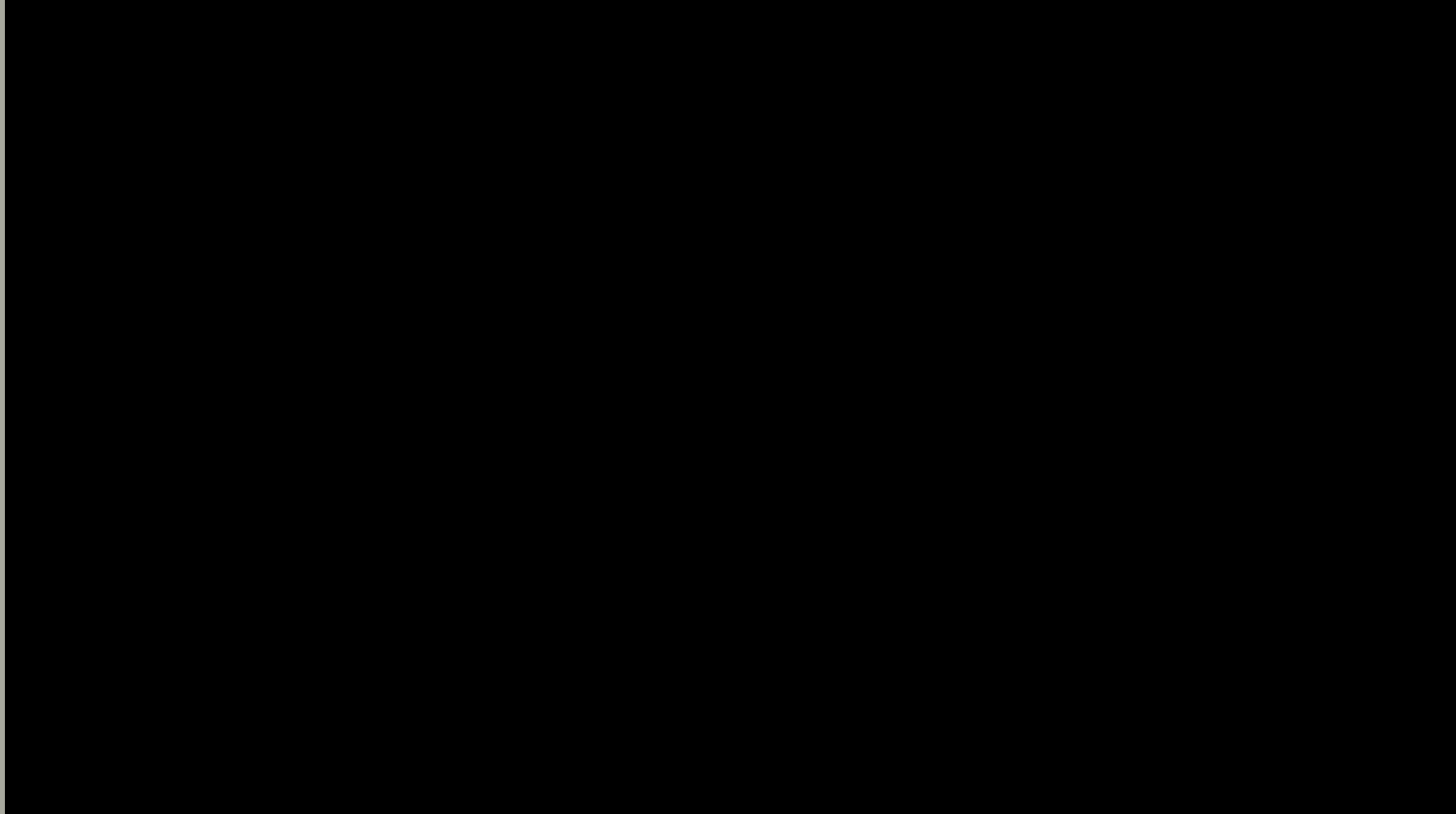
Curb Weight 6,173 lbs

EASY MILE IN OPERATION: [HTTPS://VIMEO.COM/137217228](https://vimeo.com/137217228)



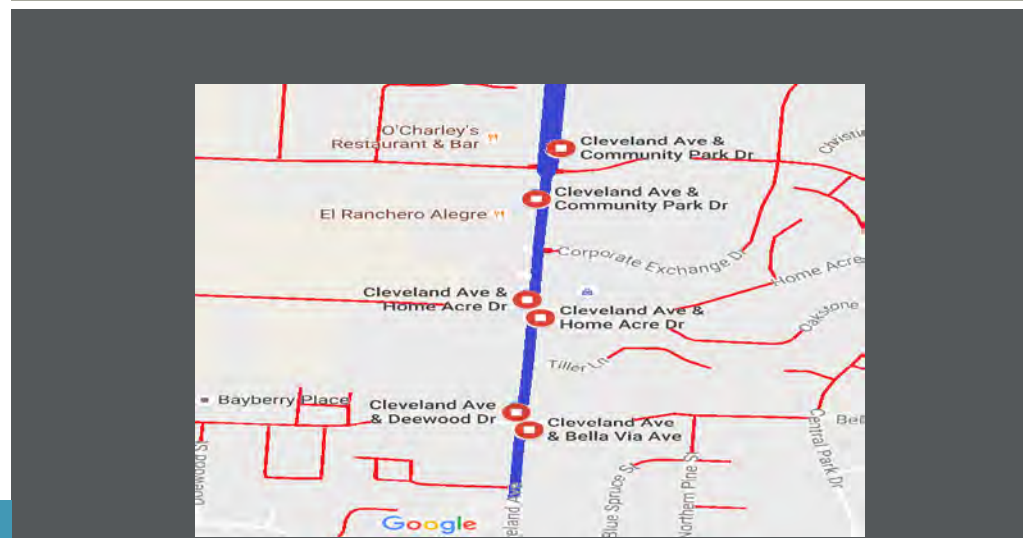
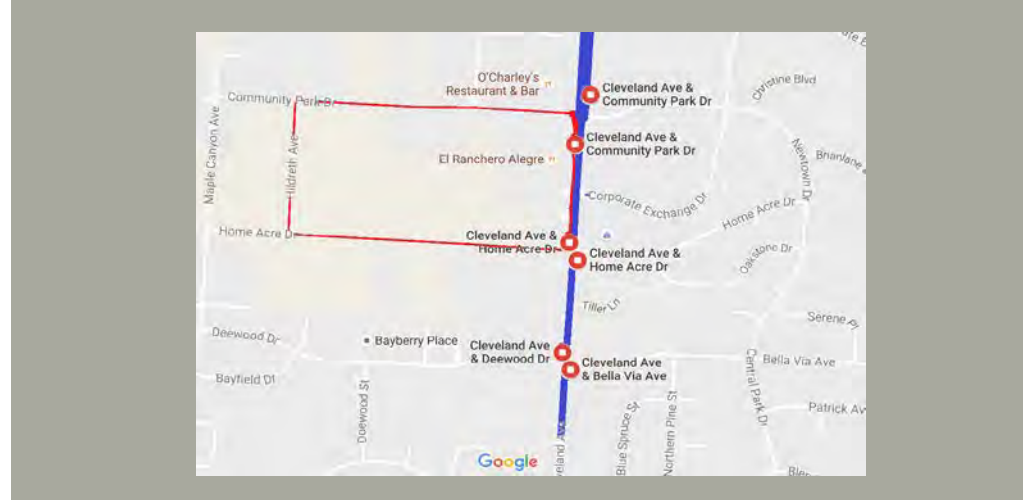
OLLI BY LOCAL MOTORS:

[HTTPS://WWW.YOUTUBE.COM/WATCH?V=9JOESWIYFEI](https://www.youtube.com/watch?v=9JOESWIYFEI)



# LIKELY OPERATIONAL DEPLOYMENTS

- First Mile/Last Mile
  - Connect travelers to existing transit options
    - Circulator
    - Hub-Spoke
- On-Demand Transit
  - Paratransit surrogate
  - Door-to-door
- Full Service Operations
  - Replaces traditional Transit



# FULL TRANSIT SERVICE OPERATIONAL MODELS

- Modular Lanes
  - Dynamically modify width of lanes to accommodate autonomous vehicles
- Exclusive Autonomous Lanes
  - Grade segregated, dedicated
  - At-grade segregated, dedicated by time-of-day
  - Mixed use lanes

Modular Lanes



HOT/HOV Managed Lanes with Transit



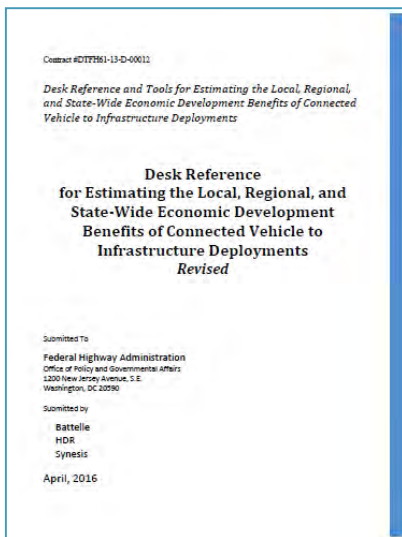
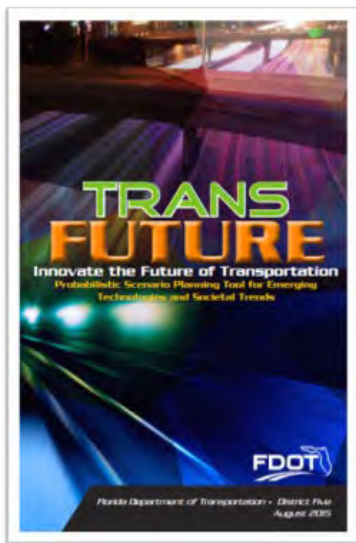
Grade Segregated Dedicated Lanes



At-Grade, Dynamic Shoulder



# AUTONOMOUS VEHICLES – IMPLICATIONS ON TRANSPORTATION



## Autonomous Vehicles – Implications for Transit

### Autonomous Vehicles Complement Transit

- Jarrett Walker (Human Transit) – “mass transit will remain crucial in places defined by a shortage of space per person. Mass transit, where densities are high enough to support it, is an immensely efficient use of space”

### Autonomous Vehicles Replace Transit

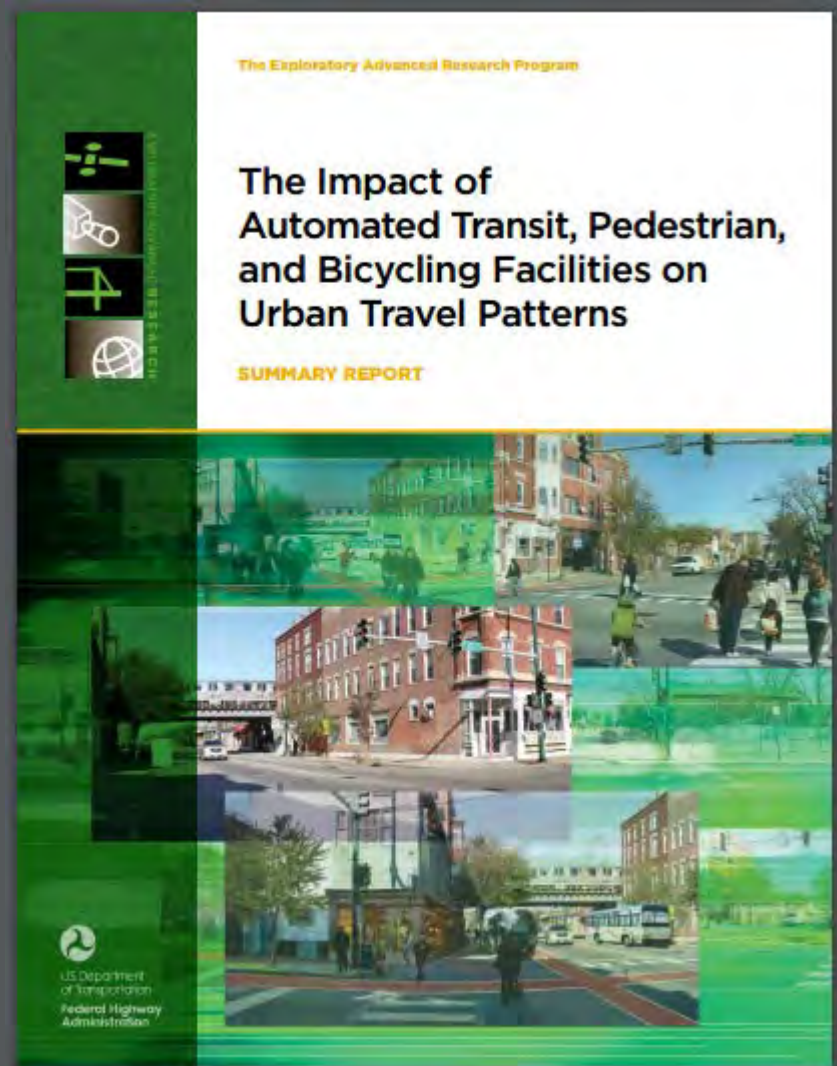
- Robin Chase (Zipcar) – Autonomous vehicles will replace traditional transit with public transit providing vouchers for trips.

### Meeting in the Middle (Austin Good)

- Emphasis on fast, high capacity fixed-route corridors
- Flex-routes in low demand areas
- Stations as transfer hubs
- No more schedules or off hours
- Less of a need for paratransit
- Ride share/transit fare integration
- Frequent & fast intercity fixed-routes

# IMPACTS OF AUTOMATED TRANSIT ON URBAN TRAVEL

- “presence of the community transit [automated first-mile/last-mile shuttle] and urban-design improvements had a marked effect on the sample population...”
- “...community shuttle produced greater change in the lower density areas...”
- “...high-frequency transit shuttles **could trigger significant shifts from driving to public transit**. Shifts to public transit may be larger in low-density neighborhoods that are more automobile-oriented and in neighborhoods where bus service is unavailable, unreliable, or infrequent.”





# POTENTIAL IMPACTS WITH MAJOR TRENDS

Factors	Auto Ownership	Trips (#)	Distance Travelled	Roadway Capacity	Safety	VMT	Speed
Automated Vehicle— Passenger	↓	↑	↑	↑	↑	↑	↑
Automated Vehicle— Commercial	—	↑	↑	↑	↑	↑	↑
Aging Population	↓	↓	↓	—	↑	↓	↑
Gen Z, Alpha Travel Behavior	↕?	↕?	↕?	—	↕?	↕?	↕?
Telecommuting	↓	↓	↕	—	↑	↓	↑
Car Sharing	↓	↕	↕	—	↑	↕	↑
Ride Hailing Service	↓	↕	↕	—	↑	↕	↑

# STRENGTHS AND WEAKNESSES

## Strengths

- Cost economical compared to traditional transit systems
- Opportunity for “personalized” and flexible service models
- Several manufacturers – more emerging rapidly
- Interoperability between existing transit and manufacturers and infrastructure
- Provides significant safety and environmental benefits

## Weaknesses

- Still relatively new technology/mode; durability for long operations has not been verified
- Requires new policies, training, and operational support
- Current technology will be challenged to move significant numbers of people expeditiously
- Acceptance by public has not been validated

## KEY CONCLUSIONS

- Autonomous vehicles with Transit are beginning to be realized
  - Adoption will continue to rise
- Autonomous transit vehicles could increase transit ridership through
  - First-Mile/Last-Mile connectivity; particularly in low density areas
  - Reduces need for parking services in central business district
- Autonomous transit vehicles not likely to replace traditional transit in the near future (10-15 years)
  - May begin to replace fixed route transit in 15-25 years
- Significant uncertainty of impact of AV on travel and capacity remains
  - Very little uncertainty of the technology itself

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